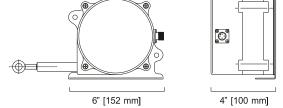


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The SR1H is part of a series of rugged, low cost, easy to install high performance string pots built for wet environments and outdoor applications.

The SR1H comes in two ranges: 0-125 inches and 0-175 inches and is the perfect low-cost CANopen solution indoor factory environments or outdoor applications. Every unit ships with a handy mounting bracket giving the user the ultimate flexibility to easily orient the measuring cable to one of four different directions.

SR1H Cable Actuated Sensor Industrial | CANopen Output Signal

Two Available Stroke Ranges: 0-125 in & 0-175 in. Rugged Polycarbonate Enclosure | Simple Installation Designed for Outdoor & IP67 environments

SPECIFICATIONS

Full Stroke Range, SR1H-125 Full Stroke Range, SR1H-175 Repeatability Resolution Input Voltage **Input Current** Maximum Velocity **Maximum Acceleration** Measuring Cable Tension Sensor **Cvcle Life** Enclosure Measuring Cable **Electrical connection Environmental Suitability Operating Temperature** Weight

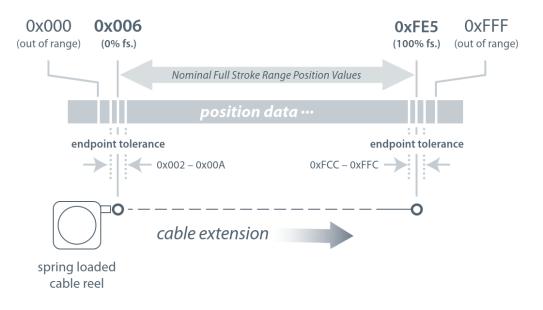
125 inches (3175 mm), maximum 175 inches (4445 mm), maximum .05% FS. 12-bit 10-36 VDC 100 mA max. 80 inches (2 meters) per second 10 g (retraction) 23 oz. (6,4 N) ±30% Plastic-hybrid precision potentiometer 250,000 (potentiometer) polycarbonate .031-inch dia. bare stainless rope M12 Connector (mating plug included) NEMA 6, IP67 -4° to 185° F (-20° to 85° C) 2.5 lbs. (1.3 Kg)

CANOpen Specifications

Communication Profile Device Type Vendor ID Baud Rate Options Date Rate Error Control PDO SDO Position Data Cam Switches EDS file** CiA 301 V 4.0.2, CANopen Slave CiA 406 V3.2, Encoder 1-127 Adjustable via dipswitch or LSS, (default set to 1) 125K (default), 250K, 500K, 1M 50ms (default) Heartbeat, Emergency Message 2 TxPDO, 0 RxPDO, no linking, static mapping 1 server, 0 client Object Dictionary 6004 Not Supported contact factory

**-objects 1018, 1A03, 2002, and 6804 in EDS file are not supported

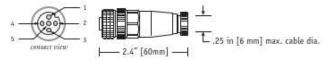
Position Data Overview:



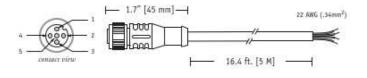
Electrical Connection:

output signal	connector pin	colorcode (cordset)
n/c	1	brown
1036 VDC	2	white
common	3	blue
CAN high	4	black
CAN Low	5	green/yellow
		a

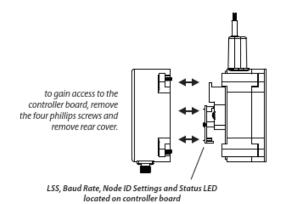
M12 Connector (included)



16 ft. Cordset (optional)



Internal Controller Board



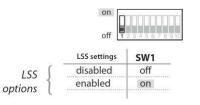
LSS, Baud Rate and Node ID settings:

LSS, Baud Rate and Node ID Settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body.

Follow the instructions on the following pages for desired settings and reinstall sensor cover.

Status LED - Indicates Operating Condition of the Potentiometer				
green	red	-		
on	flash	emergency message (high)		
off	flash	buffer (high)		
on	off	normal operating range		
flash	off	buffer (low)		
flash	on	emergency message (low)		
	1			

Settings:



LSS Settings:

IF DIP Switch 1 is set to "on" position, then LSS will be functional and uses the contents of EEPROM including Node ID and Baud Rate. If DIP Switch 1 is set to "off" position, then DIP switches will override information in EEPROM including the Node ID and Baud Rate.

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BAUD Rate:

(DxD

	baud rate	SW2	SW3
ssion (125 kbps	off	off
rate	250 kbps	on	off
	500 kbps	off	on
tions	1 Mbps	on	on

off

If DIP Switch 1 is set to "off" then BAUD rate is set via DIP switch 2 and 3 as shown:

							on	
	node ID	SW4	SW5	SW6	SW7	SW8	SW9	SW10
	Dec. Hex	(27)	(2')	(23)	(2*)	(27)	(2*)	(2")
node ID	*1 0x01	on	off	off	off	off	off	off
	2 0x02	off	on	off	off	off	off	off
node ID options 1–127	3 0x03	on	OR	off	off	off	off	off
1-177		-++		***	***			
0x01-0x7F)	126 0x7E	off	on	on	оп	on	on	on
	127 0x7F	on	no	no	OU	on	on	on

"note: Node ID =1 can also be set with ALL switches (SW4 - SW10) in the "off" position

Node ID:

If DIP Switch 1 is set to "off" then the Node ID is set via DIP switches 4 – 10 as shown below. The DIP switch settings are binary starting with switch number 4 (=20) and ending with switch number 10 (=26).

The Node ID is equal to the binary setting.

Manufacturer Objects:

Index	Sub-Index	Name	Default	Comment
2000		Raw Position Valve		This is the averaged, non-scaled value from the encoder.
2001		Emergency Buffer Distance	0.1	Emergence Message is sent when the output of the sensing potentiometer is outside it's calibrated range by more than .1% of the sensor's full measurement range (Emergency Buffer). This allows for non- repeatability of sensor and customers application. This object allows user ability to change buffer size along with transmission of Emergency Message, Manufacturer specific bit in error register set, and error added to error list.

Device Profile Area:

Index	Sub-Index	Name	Default	Comment
6000		Operating Parameters	0X0000	
6004		Position Value	0	Counts proportional to measuring cable extension. Nominal values are 0x006 with cable fully retracted and 0xFE5 with cable fully extended. Format of data in CAN message is little endian – least significant byte pair first. Therefore, 0x008 would be shown as "08 00" and 0xFE5 would be shown as "ES0F"
6400		Area State Register		Sub Number = 2 (indicates underflow or overflow per CiA406)
	0	Highest Subindex	0x01	
	1	Work Area State Channel 1	0	

Device Profile Area (cont.):

6401		Work Area Low Limit		The averaged, non-scaled (raw) encoder data below which the encoder is out of range.
	0	Highest Subindex	0x01	
	1	Work Area Low Limit Channel1	0x024	
6402		Work Area Low Limit		The averaged, non-scaled (raw) encoder data below which the encoder is out of range.
	0	Highest Subindex	0x01	
	1	Work Area Low Limit Channel1	0xF4E	
6500		Operating Status	0x000	
6501		Measuring Step	1	Position Measuring Step. Can be set by user to convert Position Value (Object 6004) to measurement units

Communication Area Profile:

Index	Sub-Index	Name	Default	Comment
1000		Device Type	0X00080196	Device Profile
1001		Error Register	0	Manufacturer Specific Error bit 7 is set when sensor is outside of calibrated range and cleared when back in range.
1003		Pre-Defined Error Field		Sub Number = 9 (lists last eight Emergency Messages)
	0	Number of Errors	0	
	1	Standard Error Field 1		
	2	Standard Error Field 2		
	3	Standard Error Field 3		
	4	Standard Error Field 4		
	5	Standard Error Field 5		
	6	Standard Error Field 6		
	7	Standard Error Field 7		
	8	Standard Error Field 8		
1005		SYNC COB-ID	0x80	
1010		Store Parameters		Sub Number = 2
1010	0	Highest Subindex	0x01	Only "Save All Parameters" features supported
	1	Save All Parameters		Write "save" or "evsa" to save parameters to EEPROM. They are automatically loaded on power up/reset. Saves the value of all R/W object dictionary entries.
1014		Emergency COB-ID	\$NodeID + 0x80	COB-ID Emergency Message
1015		Emergency Inhibit Time	0	Multiple of 100µs. Minimum time between transmissions of emergency messages
1017		Producer Heartbeat Time	0	Multiples of 1ms. Time between transmission of heartbeat messages. 0 = disabled

Communication Area Profile (cont.):

1018		Identity Object		
	0	Number of Entries	4	
	1	Vendor Id	0x2E0	
	2	Product Code	269 (decimal)	Celesco Reference # 604269
	3	Revision Number	1	
	4	Serial Number	0x0000000	
1800		Tx PDO Comm. Parameter		PDO1
	0	Number of Entries	5	
	1	COB-ID	\$NodeID + 0x108	COB-ID used by PDO1
	2	Transmission Type	254	PDO1 Tx Type; 0 = on Sync Message. 254 = Asynchronous Tx
	3	Inhibit Time	0	Multiple of 100us. Minimum time between transmissions of the PDO
	5	Event Timer	0x32	If non-zero then transmits the PDO periodically. This value is a multiple of 1ms.
1081		Tx PDO Comm. Parameter		PDO1
	0	Number of Entries	5	
	1	COB-ID	\$NodeID + 0x208	COB-ID used by PDO2
	2	Transmission Type	254	PDO2 Tx Type; 0 = on Sync Message. 254 = Asynchronous Tx
	3	Inhibit Time	0	Multiple of 100us. Minimum time between transmissions of the PDO
	5	Event Timer	0x32	If non-zero then transmits the PDO periodically. This value is a multiple of 1ms.
1A00		Tx PDO Mapping Parameter		Sub Number = 2
	0	Number of Entries	1	
	1	PDO Mapping Entry	0x60040020	Mapping Parameter
1A01		Tx PDO Mapping Parameter		Sub Number = 2
	0	Number of Entries	1	
	1	PDO Mapping Entry	0x60040020	Mapping Parameter

Changing the Cable Exit:

Changing Measuring Cable Exit

To change the direction of the measuring cable, remove the 4 mounting bracket screws and rotate bracket to one of four available positions. See figures 1 - 4 on the following pages for mounting dimensions.

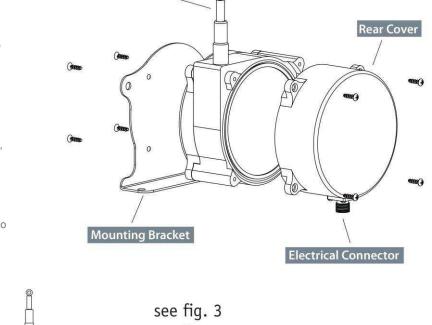
Changing Electrical Connector Direction

To change the position of the Electrical connector, remove the 4 rear cover screws and carefully separate rear cover from the sensor body.

Rotate the rear cover to desired position being careful to not tangle the wiring harness that runs to the connector.

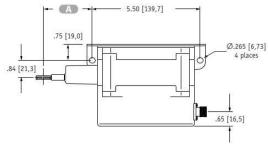
Charging Exit Direction Options:

0



Measuring Cable

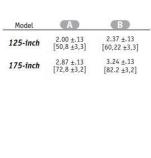




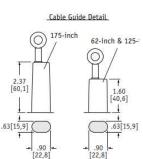
see fiq. 1

Î M

see fig. 2

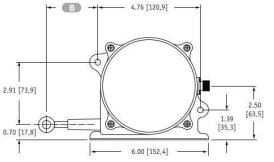


— 3.85 [97,8] max. —

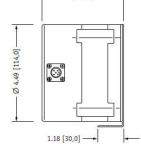


see fig. 4

0



units are in inches [mm] tolerances are ± .04 [1,0] unless otherwise noted



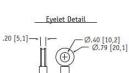


Fig. 2 – "Up" Cable Exit Direction:

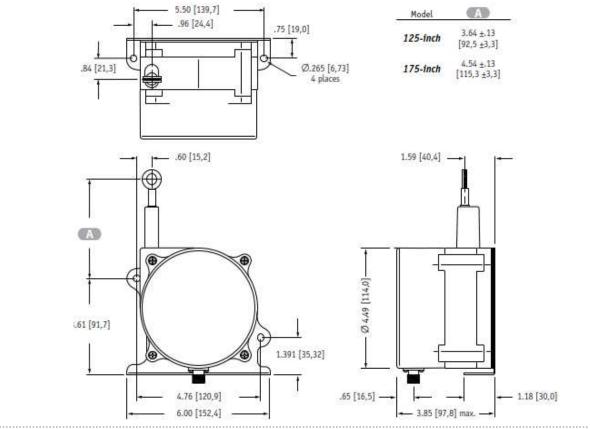
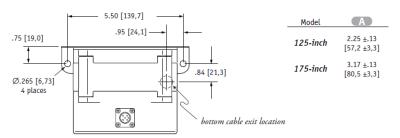
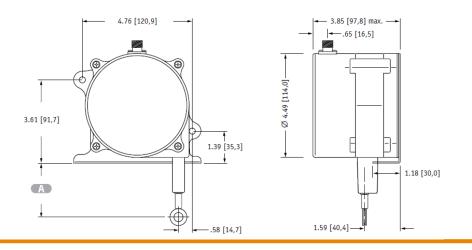
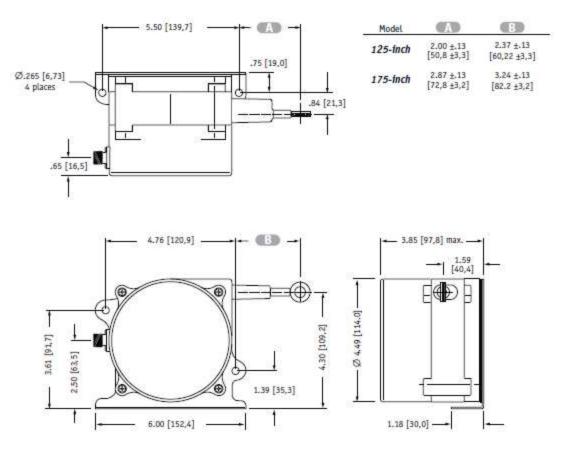


Fig. 3 – "Down" Cable Exit Direction:









units are in inches [mm] tolerances are $\pm .04$ [1,0] unless otherwise noted

Ordering Information:

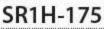


Order No. SR1H-125

- 125-inch stroke range
- CAN Open Communication
- 5-pin M12 field installable mating plug
 mounting bracket



Order No.



- 175-inch stroke range
- CAN Open Communication
- 5-pin M12 field installable mating plug

- mounting bracket



Order No. 9036810-0030

for short-run connections, optional 16-ft (5 m) long cordset with 5-pin M12 mating plug.

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